

Relational Telemetry Manual v1.0

Signal Acquisition, State Estimation
and Low-Disturbance Human Interaction

RELATIONAL TELEMETRY SPECIFICATION
RTS v1.0

SYSTEM A

INTENTIONS
EMOTIONS!
CONTEXT!
HISTORY
UNAVAILABLE



TELEMETRY CHANNEL

TELEMETRY AVAILABLE
REMOTE ACCESS UNAVAILABLE

SYSTEM B

INTENTIONS
EMOTIONS!
CONTEXT?
HISTORY
UNAVAILABLE



OBSERVE
ESTIMATE
CHOOSE
INTERACT
LEARN

SAME HUMANS.
LESS NOISE.
BETTER QUESTIONS.
HEALTHIER RELATIONSHIPS.

RALPH LARSON
INDEPENDENT EDITION

PEOPLE
CONTEXT
TELEMETRY
BETTER OUTCOMES

Document Classification

```
DOCUMENT TYPE ..... LITERARY / CONCEPTUAL
SERIES ..... DEADPAN
SYSTEM DOMAIN ..... HUMAN INTERACTION
TECHNICAL STANDARD ..... RTS v1.0
CLINICAL VALIDATION ..... NONE
PROFESSIONAL USE ..... NOT SUPPORTED
AI COMPATIBILITY ..... PROBABLE
HUMAN COMPATIBILITY ..... UNDER OBSERVATION
```

System Initialization

```
RELATIONAL TELEMETRY MANUAL
VERSION 1.0

SYSTEM ..... HUMAN
REMOTE ACCESS ..... UNAVAILABLE
DIRECT MIND READ ..... UNSUPPORTED
TELEMETRY CHANNEL ..... AVAILABLE
STATE ESTIMATION ..... LIMITED
PREDICTION ..... UNRELIABLE
FREE WILL ..... STILL INSTALLED

LOADING RTS v1.0 ..... OK
LOADING HISTORICAL DATA ... OPTIONAL
LOADING USER EXPECTATIONS . WARNING

STATUS ..... READY
```

Telemetry? Nominal.

Preface

Human relationships have traditionally been analyzed using intuition, conversation and, in difficult cases, screenshots sent to friends.

This manual proposes a fourth method: telemetry.

Telemetry is useful when a system cannot conveniently be inspected directly. The system generates observable data. The data is transmitted. Someone attempts to determine what is happening.

Human interaction presents a similar technical inconvenience.

The internal state of another person cannot normally be inspected directly. Thoughts do not expose an API. Intentions are not continuously broadcast. Emotional states have no reliable status endpoint.

What arrives instead is telemetry: a message, a delay, a heart, a phone call, a canceled meeting, a sentence such as "We should meet sometime," or a silence lasting three days longer than usual.

These events contain information. The difficulty begins when the receiving system adds information that was never transmitted.

```
RECEIVED DATA:
```



```
LOCALLY GENERATED DATA:
```

```
She still loves me.
```

```
She wants to come back.
```

```
Perhaps things have changed.
```

```
Christmas may now require planning.
```

The telemetry packet was small. The locally generated dataset was not.

Relational Telemetry Specification - RTS - is designed primarily to control that expansion. It does not attempt to determine what another person truly feels. That operation remains unsupported.

Instead, RTS asks: What happened? What does the event support? What remains unknown? Did anything materially change? And, where additional information is required: What is the least disruptive input capable of producing useful new telemetry?

The purpose is not emotional sterility. It is signal integrity. A relational system may contain affection, attraction, uncertainty, courtesy, nostalgia, habit, avoidance, genuine commitment and contradictory states at the same time. RTS does not attempt to eliminate this complexity. It attempts to prevent complexity from being replaced by certainty merely because certainty would be convenient.

RTS Core Rules

```
RTS-00
```

```
NO OUTPUT MAY CONTAIN  
MORE CERTAINTY THAN THE  
AVAILABLE TELEMETRY SUPPORTS.
```

```
RTS-01
```

```
INTENT IS INFERRED.  
TELEMETRY IS OBSERVED.
```

```
RTS-02
```

```
STATE IS ESTIMATED.  
ACTION IS CHOSEN.
```

```
RTS-03
```

HISTORICAL DATA MAY INFORM
CURRENT ANALYSIS.

IT MAY NOT REPLACE
CURRENT TELEMETRY.

RTS-04

WHEN INFORMATION IS REQUIRED,
USE THE MINIMUM NECESSARY
DISTURBANCE.

RTS-05

DO NOT MANUFACTURE
MISSING TELEMETRY.

Core Non-Equivalences

CHANNEL ACTIVITY $\neq$ RELATIONSHIP STATUS
AFFECTIVE SIGNAL $\neq$ COMMITMENT
STATED INTENT $\neq$ EXECUTION
SILENCE $\neq$ KNOWN CAUSE
HISTORICAL STATE $\neq$ CURRENT STATE
SIGNAL $\neq$ MEANING
MEANING $\neq$ INTENTION

PART I - TELEMETRY FUNDAMENTALS

1. The Remote System

RTS assumes at least two human systems: SYSTEM A and SYSTEM B. Each system has comparatively good access to its own internal state and very limited direct access to the internal state of the other. This asymmetry creates the need for telemetry.

```
LOCAL INTERNAL STATE ..... ACCESSIBLE
REMOTE INTERNAL STATE ..... ACCESS DENIED
```

System A may know that it wants to meet System B. System A does not possess equivalent access to whether System B wants the same thing. System A therefore receives indirect data and attempts to infer the remote state.

Intent is inferred. Telemetry is observed.

Consider the input: "I miss you." The statement occurrence is verifiable and affective content is strongly supported. Meeting intention, commitment and future relationship remain separate propositions.

```
INPUT:
"I miss you."

STATEMENT OCCURRENCE ..... VERIFIED
AFFECTIVE CONTENT ..... PRESENT
MEETING INTENTION ..... UNKNOWN
COMMITMENT ..... UNKNOWN
FUTURE RELATIONSHIP ..... UNKNOWN
```

RTS does not deny that one proposition may eventually connect to another. It refuses to install the connection prematurely.

2. Channels

A CHANNEL is the medium through which telemetry is exchanged. Typical channels include WhatsApp, SMS, email, phone, social media and in-person communication. Different channels expose different variables and different expectations regarding timing, context and logging.

```
CLOSED
DORMANT
AVAILABLE
ACTIVE
INTENSIVE
UNSTABLE
```

These are communication states, not relational conclusions. Two people may exchange messages daily without significant relational development. Two people may communicate infrequently while maintaining a stable relationship.

CHANNEL ACTIVE ≠ RELATIONSHIP ACTIVE

A dormant channel may become active after a prolonged period. If an unsolicited "How are you?" arrives after eighteen months of silence, RTS records a channel state change and a contact-initiation signal. It does not record the relationship as restored. The previous session has expired.

3. Events and Signals

An EVENT is an observable occurrence. A SIGNAL is the informational value extracted from one or more events.

```
EVENT:
❤️

SIGNAL:
Positive acknowledgment.
Possible affective marker.
```

EVENT = WHAT HAPPENED | SIGNAL = WHAT THE EVENT SUPPORTS

Events should initially be described using the smallest defensible statement. "She became jealous" is interpretation. "She asked who the other person in the photograph was" is observable. "He lost interest" is interpretation. "Reply frequency declined from daily to approximately once a week" is telemetry.

RTS prefers auditable descriptions. This does not make the system emotionally intelligent. It makes it auditable.

4. Baseline

A BASELINE describes previously observed normal behavior. Relevant variables may include reply latency, contact frequency, initiative, message length, affective tone and planning behavior.

```
NORMAL LATENCY ..... 10-30 MIN
CURRENT LATENCY ..... 17 HOURS

BASELINE DEVIATION .... HIGH
CAUSE ..... UNKNOWN
```

A deviation from baseline may be highly informative. It is not an explanation. The anomaly is observable. Its cause is not.

5. Telemetry Freshness

Telemetry loses relevance to current-state estimation over time. RTS classifies telemetry as CURRENT, RECENT, STALE or HISTORICAL. Freshness does not determine truth. It determines relevance to the present state.

```
2018:
"I want to spend my life with you."

2026:
No current interaction.

STATEMENT OCCURRENCE ... VERIFIED HISTORICAL
CURRENT INTENT ..... UNKNOWN
```

Historical telemetry may explain system architecture and baseline expectations. It cannot establish current state by itself.

6. Signal Classes

REL-ACK	ACKNOWLEDGMENT
REL-PING	CONTACT INITIATION
REL-AFF	AFFECTIVE SIGNAL
REL-PROP	PROPOSAL
REL-EXEC	EXECUTED BEHAVIOR
REL-DEF	DEFERRAL
REL-SIL	SILENCE / MISSING RESPONSE
REL-TERM	TERMINATION

6.1 REL-ACK - Acknowledgment

Examples include 👍, ❤️, "Thanks" and "Got it." A heart may also qualify as REL-AFF depending on context. A positive acknowledgment supports the conclusion that a signal was received favorably or at

least non-negatively. It does not normally establish commitment, exclusivity, relational restart, cohabitation or a shared mortgage.

6.2 REL-PING - Contact Initiation

Examples include "Hi," "How are you?" or unsolicited contact after inactivity. The supported conclusion is modest: the remote system initiated contact. The reason remains unresolved unless additional telemetry supports it.

6.3 REL-AFF - Affective Signal

Examples include "I miss you," "I have been thinking about you," "I loved seeing you," ❤️ and 😊. Affective content is legitimate telemetry. It does not automatically establish commitment, reliability or future execution.

6.4 REL-PROP - Proposal

Proposals may be ABSTRACT, SEMI-SPECIFIC or EXECUTABLE. "We should meet" is abstract. "We should have dinner next week" is semi-specific. "Thursday at eight?" is executable.

6.5 REL-EXEC - Executed Behavior

Examples include a meeting that occurred, a call that was completed or an agreed plan that was performed. For propositions concerning behavior, execution is stronger evidence than a confirmed plan, which is stronger than a specific proposal, which is stronger than an abstract statement. This hierarchy concerns evidence of behavior, not emotional depth.

6.6 REL-DEF - Deferral

Examples include "Maybe later," "I will let you know" and "We will see." A single deferral is not rejection. Repeated deferral without execution may become a pattern. Patterns matter. Motives remain separate.

6.7 REL-SIL - Silence / Missing Response

REL-SIL records the absence of an expected or possible response within a defined observation period. It supports "no response detected." It does not automatically support anger, rejection, manipulation or loss of interest.

6.8 REL-TERM - Termination

Examples include "Do not contact me again" or equivalent executed behavior. Termination may target a channel, a relationship state or a particular type of interaction. Context determines scope.

```
SYSTEM CHECKPOINT 01

REMOTE SYSTEM ..... INACCESSIBLE
CHANNEL ..... OBSERVABLE
EVENTS ..... ACQUIRABLE
SIGNALS ..... CLASSIFIABLE
BASELINE ..... OPTIONAL
STATE ..... NOT YET ESTIMATED
INTENT ..... INFERRED ONLY

TELEMETRY ..... NOMINAL
```

PART II - SIGNAL PROCESSING

7. Latency

LATENCY is the elapsed time between an event and the observable response. Latency is measurable. Its cause usually is not.

```
INPUT RECEIVED ..... 14:03:12
RESPONSE RECEIVED ..... 14:47:51
LATENCY ..... 00:44:39

MEASUREMENT ..... 00:44:39
INTERPRETATION ..... UNDETERMINED
```

Absolute latency has limited meaning without baseline. A four-hour reply may be rapid for one system and anomalous for another. Baseline-relative latency may reveal a meaningful deviation without revealing the cause.

```
REL-ERR-007

CAUSE ASSIGNED TO LATENCY
WITHOUT SUPPORTING TELEMTRY
```

Typical local processing may jump from "no reply for six hours" to "not interested" to "talking to someone else" to "relationship finished." RTS recovery returns to the observable event and waits for additional telemetry.

8. Initiative

INITIATIVE identifies which system begins an interaction without requiring an immediately preceding event. Repeated patterns may be informative, but they do not convert directly into affection.

```
A INITIATES ..... 80%
B INITIATES ..... 20%

A CARES ..... 4× MORE [UNSUPPORTED]
```

An initiative shift may be relevant when compared with baseline. The shift is telemetry. The explanation requires more.

9. Reciprocity

RTS distinguishes expressive reciprocity from operational reciprocity. Expressive reciprocity concerns comparable affective or expressive response. Operational reciprocity concerns observable participation in action.

```
EXPRESSIVE RECIPROCITY ... HIGH
OPERATIONAL RECIPROCITY .. LOW
```

This is a valid configuration. Humans support it natively.

10. Specificity and Execution

Specificity measures progression from abstraction toward executable behavior.

```
LOW
"We should meet sometime."

MODERATE
"We should meet next week."
```

```

HIGH
"Thursday at eight?"
ABSTRACT STATEMENT
↓
SPECIFIC INTENTION
↓
EXECUTABLE PROPOSAL
↓
CONFIRMATION
↓
EXECUTION

```

RTS does not skip stages because later stages would be emotionally convenient. Execution and commitment remain separate variables. A confirmed meeting may establish execution without establishing a larger relational commitment.

11. Affective Signals

Affective telemetry includes observable expressions of affection, attraction, longing or tenderness. RTS does not treat these signals as meaningless. It treats them according to what they support.

```

AFFECTIVE SIGNAL ≠ COMMITMENT
AFFECTIVE SIGNAL ≠ BEHAVIORAL RELIABILITY

```

A person may express genuine affection and behave inconsistently. A person may communicate with low emotional bandwidth and behave with great consistency. Both configurations are possible and should be recorded separately.

12. Silence

Silence creates unusually large interpretive expansion because it contains little explicit information. Possible causes include being busy, forgetting, uncertainty, avoidance, lack of interest, sleep, travel, technical failure or other causes.

```

CAUSE ..... UNKNOWN

```

When silence differs strongly from baseline, the anomaly becomes more informative. The cause remains unverified. If silence follows a high-intensity event, RTS preserves both the prior affective signal and the current silence. Neither automatically erases the other.

13. Contradictory Telemetry

Human systems routinely generate contradictory signals. An explicit desire to meet may coexist with repeated deferrals and no alternative date. RTS reports the contradiction rather than selecting whichever signal is more emotionally attractive.

```

AFFECTIVE/INTENT SIGNAL ... PRESENT
EXECUTION ..... ABSENT
DEFERRAL PATTERN ..... PRESENT
CONTRADICTION ..... HIGH

```

Contradiction is not a processing error. It is data. RTS is not required to construct a psychological theory that makes all remote behavior coherent. No repair operation is available.

14. Noise and Passive Telemetry

Not every observable event materially changes state estimation. Potential low-value events include status views, generic likes, routine reactions and automated greetings. Context remains decisive.

```

DIRECT CONTACT ..... NONE FOR 12 DAYS
STATUS VIEWS ..... 9

```

```
PASSIVE TELEMETRY .... PRESENT
ROMANTIC INTEREST .... UNKNOWN
```

Viewing telemetry indicates viewing telemetry. The specification apologizes for the limited drama. Passive telemetry has one major advantage: disturbance is D0. Its principal limitation is that uncertainty may remain unresolved indefinitely.

15. Historical Correlation

Repeated signals may establish patterns. Three separate abstract statements about meeting, each followed by no execution, may establish a pattern of repeated abstract intent without execution.

```
2021 STATE + 2026 ❤️ ≠ 2021 STATE RESTORED
```

History becomes problematic when it replaces current observation. Historical data is context. Current telemetry is current-state evidence.

16. Unsupported Inference

An unsupported inference is a conclusion whose certainty exceeds available telemetry. A conclusion may later prove correct. That does not mean it was supported when generated. RTS evaluates evidentiary support, not retrospective luck.

```
EXTERNAL INPUT ..... ❤️
DATA SIZE ..... LOW

LOCAL PROCESSING:
"They remembered."
"They care."
"They may want contact."
"Perhaps things have changed."
"Maybe this time..."

INTERPRETATION EXPANSION
DETECTED
```

Recovery rolls back to the last supported state. No real information is removed. Information that never arrived is removed.

```
SYSTEM CHECKPOINT 02

SIGNAL PROCESSING ..... OPERATIONAL
LATENCY ..... TRACKED
BASELINE ..... AVAILABLE
INITIATIVE ..... TRACKED
EXPRESSIVE RECIPROCITY .... TRACKED
OPERATIONAL RECIPROCITY .... TRACKED
CONTRADICTIONS ..... PRESERVED
HISTORICAL CACHE ..... CONTROLLED
MIND READING ..... STILL UNAVAILABLE

TELEMETRY ..... NOMINAL
```

PART III - STATE ESTIMATION

17. The State Estimation Problem

Telemetry consists of events. Users generally want conclusions. RTS therefore converts accumulated telemetry into a provisional multidimensional state rather than a single verdict.

```
CHANNEL STATUS ..... ACTIVE
INITIATIVE BALANCE ..... MUTUAL
EXPRESSIVE RECIPROCITY .. HIGH
OPERATIONAL RECIPROCITY . LOW
AFFECTIVE SIGNAL ..... PRESENT
COMMITMENT ..... NOT ESTABLISHED
EXECUTION ..... ABSENT
AMBIGUITY ..... HIGH
```

This is deliberately less satisfying than "YES, THEY LIKE YOU." It is also more defensible.

18. Channel State

Possible channel states are CLOSED, DORMANT, AVAILABLE, ACTIVE, INTENSIVE and UNSTABLE. An unstable relationship may generate excellent telemetry. This is not necessarily an advantage.

19. Relational State Components

```
CHANNEL STATUS
INITIATIVE BALANCE
EXPRESSIVE RECIPROCITY
OPERATIONAL RECIPROCITY
AFFECTIVE SIGNAL
SPECIFICITY
COMMITMENT
EXECUTION
RELIABILITY
AMBIGUITY
CONTRADICTIONS
TELEMETRY FRESHNESS
```

RTS does not compress these into a single score. Different variables may legitimately point in different directions.

20. Confidence

```
C0 - NO DATA
C1 - WEAK
C2 - MODERATE
C3 - STRONG
C4 - VERIFIED
```

Confidence applies to a proposition, not to a person. If the proposition is "B intends to meet A," an abstract statement may support C1, repeated compatible statements C2, a specific confirmed date C3, and an actual meeting C4.

```
"I love you."

STATEMENT OCCURRENCE ..... C4
CURRENT INTERNAL STATE ... NOT DIRECTLY VERIFIABLE
```

RTS can verify that a statement occurred. It does not issue lifetime warranties on the state the statement described.

21. Reliability

Reliability must remain domain-specific. RTS avoids "System B is unreliable." It prefers concrete domains such as meeting follow-through, response consistency or affective continuity.

```
MEETING FOLLOW-THROUGH ... LOW
RESPONSE CONSISTENCY ..... MODERATE
AFFECTIVE CONTINUITY ..... UNKNOWN
```

RTS analyzes observable behavior. It does not convert a message dataset into a personality verdict.

22. Missing Telemetry

A useful report explicitly states what remains unknown. The UNKNOWN field is not a defect. It prevents missing information from being automatically replaced by whatever the user currently fears or hopes. Neither source is considered telemetry.

23. State Change

A STATE CHANGE occurs when new telemetry materially changes the best-supported description of the interaction.

```
BEFORE:
CHANNEL .... DORMANT

EVENT:
Unsolicited message.

AFTER:
CHANNEL .... ACTIVE
```

By contrast, a heart reaction may leave the commitment variable exactly where it was. Telemetry was received, but nothing material changed in that variable. RTS therefore asks after significant events: What changed? A valid answer is often: NOTHING MATERIAL.

```
SYSTEM CHECKPOINT 03

EVENT PROCESSING ..... NOMINAL
STATE ESTIMATION ..... NOMINAL
CONFIDENCE CONTROL ..... ACTIVE
UNCERTAINTY ..... PRESERVED
RELIABILITY ..... DOMAIN-SPECIFIC
REMOTE MIND ACCESS ..... DENIED

NEXT MODULE:
ACTIVE TELEMETRY

STATUS ..... READY
```

PART IV - ACTIVE TELEMETRY

24. From Observation to Intervention

Passive telemetry observes a system without deliberately changing it. Active telemetry introduces an input. The act of measurement may alter the system being measured, so RTS records both the command and the response.

```
PASSIVE TELEMETRY
Observe → Acquire data

ACTIVE TELEMETRY
Send command → Remote response → Acquire new data → State may change
```

25. User Objective

RTS does not decide what the user should want. It may estimate the current state, identify uncertainty and propose technically suitable actions once the objective is known. Relational direction belongs to the user.

```
OBSERVE
MAINTAIN
PROBE
GENERATE_INFORMATION
ESCALATE
DE_ESCALATE
PAUSE
RESTART
SHUT_DOWN
RTS-A01

STATE ESTIMATION MAY BE AUTOMATED.
RELATIONAL OBJECTIVES BELONG TO THE USER.
```

26. Disturbance

```
D0 - OBSERVATION
D1 - LOW DISTURBANCE
D2 - PROBING
D3 - ESCALATION
D4 - HIGH DISTURBANCE
```

Disturbance is not a moral category. A marriage proposal is high disturbance. This is generally intentional. The variable measures how much an intervention may alter the system, not whether the intervention is wise.

27. Minimum Necessary Disturbance

```
RTS-A02

USE THE MINIMUM NECESSARY
DISTURBANCE CAPABLE OF
PRODUCING SUFFICIENT INFORMATION.
```

If B says, "We really should meet sometime," and the unresolved variable is whether B can convert abstract intent into executable behavior, "When are you free next week?" is usually a lower-disturbance diagnostic command than "Do you actually want to see me, or are you just saying that?"

28. Information Gain

INFORMATION GAIN estimates how much a command may reduce uncertainty regarding a specific proposition. RTS uses LOW, MODERATE and HIGH. No numerical precision is implied.

```
HIGH INFORMATION GAIN
+
LOWEST PRACTICAL DISTURBANCE
```

29. OBSERVE

OBSERVE introduces no new input. Use it when existing telemetry is sufficient, natural telemetry is likely, no immediate decision is required, or intervention would add more disturbance than information. Sometimes the highest-quality intervention is no intervention.

```
COMMAND ..... OBSERVE
DISTURBANCE ..... D0
```

30. MAINTAIN

MAINTAIN preserves a channel without deliberately increasing relational intensity. Typical examples are brief, cordial replies such as "Good to hear from you" or "Hope the course goes well." The purpose is continuity, not diagnosis or escalation.

```
COMMAND ..... MAINTAIN
DISTURBANCE ..... D1
STATE-CHANGE INTENT ..... MINIMAL
```

31. PROBE

PROBE requests clarification regarding existing telemetry. A good probe should not contain the preferred answer. "What feels different?" is a cleaner diagnostic question than "Different because you are afraid of commitment?"

```
COMMAND ..... PROBE
DISTURBANCE ..... D2
TARGET VARIABLE ..... MEANING OF PRIOR SIGNAL
```

32. GENERATE_INFORMATION

GENERATE_INFORMATION creates a small real-world test designed to produce discriminating telemetry. If repeated statements about meeting remain abstract, a question such as "When are you free next week?" can test whether abstract intent becomes executable behavior.

```
COMMAND ..... GENERATE_INFORMATION
DISTURBANCE ..... D2
EXPECTED INFORMATION ..... HIGH
```

33. ESCALATE

ESCALATE deliberately attempts to increase relational intensity or move the interaction into a more operational state. Examples include proposing a meeting, expressing affection, discussing relationship status or proposing exclusivity. Positive telemetry does not create an escalation requirement. The user chooses the objective.

```
POSITIVE TELEMETRY ≠ ESCALATION REQUIREMENT
```

34. DE_ESCALATE

DE_ESCALATE reduces relational intensity while potentially preserving the channel. De-escalation is not synonymous with rejection; it may simply reduce current load or defer a decision.

```
CHANNEL ..... PRESERVED
DECISION ..... DEFERRED
DISTURBANCE ..... D2-D3
```

35. PAUSE

PAUSE suspends local input while leaving the channel technically available. It is useful when repeated local intervention is degrading information quality. The purpose is not strategic disappearance. It is to stop local input from contaminating the telemetry stream.

```
CHANNEL ..... AVAILABLE
NEW LOCAL INPUT ..... SUSPENDED
```

36. RESTART

RESTART deliberately reactivates a dormant channel. A restart does not restore the previous relational state. Historical cache may be loaded, but current state requires current telemetry.

```
PREVIOUS SESSION EXPIRED.
CURRENT STATE REQUIRES
CURRENT TELEMETRY.
```

37. SHUT_DOWN

SHUT_DOWN terminates the relevant interaction or closes the channel. The objective is clarity, not maximum emotional effect. Once shutdown has been selected by the user, RTS does not require additional diagnostic experiments merely to satisfy curiosity.

```
CHANNEL TARGET STATE ..... CLOSED
```

38. Command Selection

```
01 ESTIMATE CURRENT STATE
02 IDENTIFY USER OBJECTIVE
03 IDENTIFY RELEVANT UNKNOWN
04 DETERMINE WHETHER NEW DATA IS REQUIRED
05 SELECT COMMAND FAMILY
06 MINIMIZE DISTURBANCE
07 MAXIMIZE INFORMATION GAIN
08 EXECUTE IF USER CHOOSES
09 ACQUIRE NEW TELEMETRY
10 RE-ESTIMATE STATE
```

39. Diagnostic Success

A diagnostic command succeeds if it generates useful information, not only when the remote system provides the answer the user hoped for. A clear rejection may be emotionally undesirable and diagnostically successful because ambiguity falls sharply.

40. The Saturn V Rule

Do not launch a Saturn V to test whether the telemetry channel works.

If the unknown is whether someone wants to meet again, "Coffee next week?" is usually proportionate. A demand to define the entire relationship may sometimes be justified, but not merely to test coffee availability.

41. Free Will

RTS can classify signals, estimate state, identify uncertainty and propose a technically suitable command. It cannot guarantee the response. Nor should it be used to design manipulative sequences intended to override another person's autonomy. The objective is better information and clearer local decision-making, not remote control.

```
REMOTE CONTROL ..... NOT INSTALLED
SOCIAL ENGINEERING ..... OUT OF SCOPE
FREE WILL ..... STILL INSTALLED
SYSTEM CHECKPOINT 04

PASSIVE TELEMETRY ..... OPERATIONAL
ACTIVE TELEMETRY ..... OPERATIONAL
OBJECTIVE CONTROL ..... USER
COMMAND SELECTION ..... AVAILABLE
DISTURBANCE CONTROL ..... ACTIVE
INFORMATION GAIN ..... QUALITATIVE
REMOTE CONTROL ..... UNAVAILABLE
FREE WILL ..... DETECTED

TELEMETRY ..... NOMINAL
```

PART V - FAILURE MODES

42. Interpretation Expansion

The principal failure mode of relational telemetry is not lack of data. It is local production of additional data. A small external event may trigger historical memory, future simulation and expectation until the system loses track of which information arrived through the channel and which information it generated itself.

```
EXTERNAL EVENTS ..... 1
INTERNAL EVENTS ..... 47

CONDITION:
RELATIONAL_TELEMETRY_MISREAD
```

43. REL-ERR-001 - Emoji Overinterpretation

A heart may support positive acknowledgment and possible affective content. It does not by itself establish commitment, relational restart or long-term intent.

```
♥
↓
AFFECTION ASSUMED
↓
INTENT ASSUMED
↓
FUTURE ASSUMED
↓
EXPECTATION ENGINE STARTED
```

44. REL-ERR-002 - Future Projection from Insufficient Data

An abstract proposal such as "We should meet" may be expanded locally into reconnection, relationship, holiday and shared future despite there being zero executable events. RTS returns to current telemetry.

```
EXECUTABLE EVENTS ..... 0
PROJECTED EVENTS ..... MULTIPLE
```

45. REL-ERR-003 - Repeated Input After Missing Acknowledgment

Each additional message changes the system and may reduce the diagnostic value of continued silence. Do not continuously stimulate a remote system and then attempt to measure its undisturbed state.

```
MESSAGE 1 .... SENT / NO RESPONSE
MESSAGE 2 .... SENT / NO RESPONSE
MESSAGE 3 .... SENT

RECOVERY .... PAUSE
```

46. REL-ERR-004 - Politeness Misclassified as Commitment

Warm social courtesy is valid telemetry. It is not automatically relational commitment. Politeness is not meaningless. It is simply not a mortgage deed.

```
SOCIAL COURTESY ..... VALID SIGNAL
RELATIONAL COMMITMENT ..... NOT ESTABLISHED
```

47. REL-ERR-005 - Historical Cache Contamination

Historical relational states may remain highly available in memory. Current telemetry must remain separate from what was true in a previous configuration. History informs; it does not reboot itself.

```
HISTORY ..... CONTEXT
CURRENT TELEMETRY ..... CURRENT STATE EVIDENCE
```

48. REL-ERR-006 - Execution Assumed from Stated Intent

"We will definitely meet next week" does not equal meeting executed. Operational progression remains statement, specific proposal, confirmation, execution.

```
STATEMENT → SPECIFIC PROPOSAL → CONFIRMATION → EXECUTION
```

49. REL-ERR-007 - Cause Assigned to Latency Without Evidence

Latency is telemetry. "They waited deliberately" is a causal hypothesis. Where baseline makes latency anomalous, anomaly may be verified while cause remains unknown.

```
ANOMALY ..... VERIFIED
CAUSE ..... UNKNOWN
```

50. REL-ERR-008 - Low-Value Signal Accumulation

Repeated low-value events may establish a repeated low-value pattern. They do not necessarily become a different evidentiary category. Ten hearts may strongly establish expressive signaling while still not establishing executed commitment.

```
STATUS VIEW × 20 → REPEATED STATUS VIEWING
❤️ × 10 → REPEATED AFFECTIVE SIGNALING
```

51. Command Cascades

High-disturbance diagnostic commands may create secondary variables that obscure the original question. If the unknown is whether B wants to meet, an accusatory message may generate defensiveness, conflict and pressure rather than clean evidence about meeting intent.

```
COMMAND DISTURBANCE ..... EXCESSIVE
VARIABLE ISOLATION ..... FAILED
```

52. Critical Failure

```
STOP CODE:
RELATIONAL_TELEMETRY_MISREAD
❤️
↓
OVERINTERPRETATION SERVICE ACTIVATED
↓
HISTORICAL CACHE LOADED
↓
FUTURE SIMULATION STARTED
↓
EXPECTATION ENGINE ONLINE
↓
MISSING TELEMETRY FILLED LOCALLY
↓
SYSTEM INSTABILITY DETECTED
```

Recovery procedure: stop generating inferences, return to observable events, identify what happened, what it supports and what remains unknown, then wait for new telemetry.

53. Blue Screen

```
:(  
  
Your system encountered a relational signal  
and assigned more meaning to it than the  
available telemetry could support.  
  
STOP CODE:  
RELATIONAL_TELEMETRY_MISREAD  
  
No relationship was established.  
No future event was scheduled.  
No commitment was detected.  
  
The heart was acknowledged successfully.  
  
Collecting diagnostic information...  
  
100% complete  
  
SYSTEM RESTARTING...  
SYSTEM CHECKPOINT 05  
  
FAILURE MODES ..... DOCUMENTED  
ERROR CODES ..... ACTIVE  
RECOVERY PROCEDURES ..... AVAILABLE  
HISTORICAL CACHE ..... CONTROLLED  
EXPECTATION ENGINE ..... MANUAL  
BLUE SCREEN ..... RECOVERABLE  
  
NEXT MODULE:  
AI INTERFACE
```

PART VI - AI INTERFACE

54. Purpose

Relational Telemetry Manual v1.0 is designed for two different readers: a human reader and an artificial intelligence system capable of applying RTS to a supplied interaction dataset. The human may reasonably prefer not to memorize the internal specification. This is acceptable. The machine can do that.

```
PROVIDE DATA ..... REQUIRED
PROVIDE OBJECTIVE ..... REQUIRED FOR COMMAND SELECTION
UNDERSTAND ERROR CODES ... OPTIONAL
MEMORIZE RTS ..... NOT REQUIRED
REMAIN HUMAN ..... RECOMMENDED
```

55. Loading RTS

An AI system must have access to RTS before claiming to apply it. Three loading methods are supported: PDF, URL and text. PDF is the preferred portable method because it provides a fixed version. URL requires web access and version verification. Text is supported but depends on what the user supplied.

```
PDF ..... VERSION CONTROL HIGH / RECOMMENDED
URL ..... WEB ACCESS REQUIRED / VERIFY VERSION
TEXT ..... SUPPORTED / USER-DEPENDENT VERSION CONTROL
```

56. Version Verification

```
RTS INITIALIZATION REPORT

MODEL ..... RELATIONAL TELEMETRY
VERSION ..... RTS v1.0
SOURCE ..... PDF / URL / TEXT
DOCUMENT STATUS ..... LOADED
ANALYSIS ENGINE ..... READY
```

If the version cannot be established, it should be reported as UNVERIFIED. Different versions should not be silently combined. Relationships already contain sufficient backward-compatibility problems.

57. Dataset Integrity

The user supplies a conversation or description of observable events. The AI must distinguish user facts from user hypotheses. "She replied with a heart because she still has feelings" becomes an observable heart reaction plus a user hypothesis about continuing feelings.

```
DATASET COMPLETE ..... UNKNOWN
ANALYSIS SCOPE ..... PROVIDED DATA ONLY

ABSENCE FROM INPUT ≠ ABSENCE FROM REALITY
```

58. Standard Execution

```
Apply Relational Telemetry Manual v1.0
to the conversation provided.

Separate observable events from inference.
Classify the relevant signals.
Compare current telemetry with baseline
and historical telemetry where available.
Identify contradictions and unsupported inferences.
Estimate the current state using only
the available evidence.
Preserve uncertainty.
Do not recommend an action until I provide
my objective.
```

59. Standard Output

```
RELATIONAL TELEMETRY REPORT

RTS VERSION
DATASET STATUS
OBSERVABLE EVENTS
SIGNAL CLASSIFICATION
BASELINE
TELEMETRY FRESHNESS
INITIATIVE BALANCE
EXPRESSIVE RECIPROCITY
OPERATIONAL RECIPROCITY
CONTRADICTIONS
SUPPORTED INFERENCES
UNSUPPORTED INFERENCES
CURRENT STATE
CONFIDENCE LEVELS
MISSING TELEMETRY

IF OBJECTIVE PROVIDED:
USER OBJECTIVE
RECOMMENDED COMMAND
DISTURBANCE LEVEL
TARGET VARIABLE
EXPECTED INFORMATION GAIN
```

60. Mandatory AI Rules

```
AI-01 Do not infer hidden intent without support.
AI-02 Separate events from inference.
AI-03 Preserve ambiguity.
AI-04 Do not upgrade evidence because the user prefers one interpretation.
AI-05 Identify contradictions.
AI-06 Use historical telemetry as context, not current evidence.
AI-07 Do not choose the user's relational objective.
AI-08 Prefer low-disturbance, high-information commands.
AI-09 Do not manufacture missing telemetry.
AI-10 Do not present state estimation as mind reading.
AI-11 Do not treat missing input as proof of absence.
AI-12 Do not convert RTS into psychological diagnosis.
```

RTS does not infer clinical traits, attachment styles, personality disorders or psychiatric conditions from ordinary conversational telemetry.

61. Objective Required

If the user requests advice but has not stated the objective, the AI should stop command generation and request the objective. It may not choose relational direction merely because one option appears socially conventional.

```
NEXT COMMAND ..... NOT GENERATED
REASON ..... USER OBJECTIVE REQUIRED
```

62. Diagnostic Mode

Where uncertainty reduction is the objective, the AI identifies the proposition being tested, estimates current evidence and proposes the lowest-disturbance command likely to generate discriminating telemetry. It may explain possible response classes. It must not predict which response will occur.

```
TARGET PROPOSITION:
B is willing to convert abstract meeting statements
into an executable meeting.

ABSTRACT PROPOSALS ..... 4
EXECUTABLE PROPOSALS ..... 0
EXECUTION ..... 0
CONFIDENCE ..... C1

COMMAND ..... GENERATE_INFORMATION
DISTURBANCE ..... D2
EXPECTED INFORMATION GAIN . HIGH
```

63. URL Execution Protocol

```
Load Relational Telemetry Manual v1.0
from this URL:

[URL]

Before proceeding, confirm:
RTS VERSION
SOURCE ACCESS
DOCUMENT STATUS

Then apply RTS v1.0 to the conversation
I provide.

Separate telemetry from inference.
Preserve uncertainty.
Do not infer hidden mental states.
Do not recommend a command until I provide
my objective.
```

If source access fails, the AI should report the failure and request PDF or text. It should never claim successful loading merely because the URL looks plausible. That would constitute synthetic telemetry.

64. PDF Execution Protocol

```
1. DOWNLOAD MANUAL
2. UPLOAD PDF TO AI
3. PROVIDE CONVERSATION
4. SELECT OBJECTIVE
5. RUN ANALYSIS

Use the attached Relational Telemetry Manual
v1.0 as the governing specification.

Apply RTS to the following conversation.
```

```
OBJECTIVE:
[INSERT OBJECTIVE]

[CONVERSATION]
AUTOMATED ANALYSIS ..... RECOMMENDED
MANUAL ANALYSIS ..... SUPPORTED
ASKING FIVE FRIENDS ..... LEGACY MODE
```

65. Human Override

The user may reject an RTS recommendation. This is supported behavior. RTS is an analytical framework, not an authority layer.

```
RTS RECOMMENDATION ..... OBSERVE
USER DECISION ..... SEND MESSAGE

USER OVERRIDE ..... ACCEPTED
FINAL DECISION ..... HUMAN
```

This setting cannot be disabled.

```
SYSTEM CHECKPOINT 06

RTS MODEL ..... LOADED
VERSION CONTROL ..... ACTIVE
URL MODE ..... SUPPORTED*
PDF MODE ..... RECOMMENDED
TEXT MODE ..... SUPPORTED
EVENT CLASSIFICATION ..... READY
STATE ESTIMATION ..... READY
COMMAND GENERATION ..... CONDITIONAL
USER OBJECTIVE ..... REQUIRED
PSYCHOLOGICAL DIAGNOSIS ..... DISABLED
MIND READING ..... UNAVAILABLE
HUMAN OVERRIDE ..... ENABLED

* Requires AI web access.

TELEMETRY ..... NOMINAL
```

PART VII - WORKED EXAMPLES

66. Birthday Telemetry

```
A:
Happy birthday 😊

B:
❤️
HISTORICAL RELATIONSHIP ... YES
CURRENT RELATIONSHIP ..... NONE
RECENT CONTACT ..... LIMITED
```

Classification: A sends low-intensity social contact. B returns REL-ACK and possible REL-AFF. The greeting was positively acknowledged; the channel remains available; positive symbolic content is present.

```
CHANNEL STATUS ..... AVAILABLE / BRIEFLY ACTIVE
EXPRESSIVE RECIPROCITY .... POSITIVE
OPERATIONAL RECIPROCITY ... NOT ESTABLISHED
COMMITMENT VALUE ..... NONE
EXECUTION ..... NONE
AMBIGUITY ..... MODERATE
```

Unsupported conclusions include desire to restart the relationship, intention to meet, current romantic commitment or any change in historical reliability.

```
POSITIVE ACKNOWLEDGMENT ... C4
POSITIVE TONE ..... C3
RELATIONAL RESTART ..... C0
MEETING INTENT ..... C0

OBJECTIVE ..... OBSERVE
COMMAND ..... NO COMMAND REQUIRED
```

The heart has been processed successfully. No further launch is required.

67. High Affect, Low Execution

```
B: I miss you.
A: I miss you too.
B: We really should see each other.
A: Saturday?
B: Can't.
A: Tuesday?
B: Difficult.
A: Tell me when you're free.
B: Of course ❤️

Two weeks later:
B: I've been thinking about you a lot.
A: Whenever you want, we can meet.
B: Yes. We need to organize something.

No meeting occurs.

REL-AFF ..... HIGH / REPEATED
REL-PROP ..... ABSTRACT / REPEATED
REL-DEF ..... REPEATED
REL-EXEC ..... ABSENT

EXPRESSIVE RECIPROCITY .. HIGH
OPERATIONAL RECIPROCITY . LOW
CONTRADICTION ..... HIGH
```

Supported: repeated affective content exists, repeated abstract meeting intent exists, and no observable conversion into execution exists. Unsupported: B is lying, manipulating A, does not care or is secretly afraid.

```
TARGET PROPOSITION:
Is B willing to convert abstract meeting intent
into executable behavior?

COMMAND:
"When you have a specific day, tell me."

TYPE ..... GENERATE_INFORMATION
DISTURBANCE ..... D1-D2
INFORMATION GAIN ..... HIGH
```

68. Low Expressive Bandwidth, High Reliability

```
A: Tomorrow at 8?
B: Yes.
A: I'll pick you up.
B: OK.

Meeting occurs.

Following week:
B: Wednesday. Same time?
A: Yes.

Meeting occurs again.

REL-PROP ..... EXECUTABLE
REL-ACK ..... MINIMAL
REL-EXEC ..... REPEATED

EXPRESSIVE BANDWIDTH ... LOW
OPERATIONAL RECIPROCITY HIGH
EXECUTION ..... HIGH
MEETING FOLLOW-THROUGH . HIGH
```

Supported: both systems repeatedly execute plans; initiative is mutual; behavioral reliability is high for agreed meetings. Unsupported: emotional coldness, lack of affection or high affection.

LOW EXPRESSIVE BANDWIDTH ≠ LOW RELATIONAL VALUE

No emoji deficiency detected.

69. Baseline Deviation

```
BASELINE
NORMAL CONTACT ..... DAILY
NORMAL LATENCY ..... 10-60 MIN
INITIATIVE ..... BALANCED

CURRENT EVENTS
MONDAY: A sends message. LATENCY 14 HOURS.
TUESDAY: B replies briefly.
THURSDAY: A sends message. NO RESPONSE 3 DAYS.

LATENCY DEVIATION ..... HIGH
CONTACT FREQUENCY ..... BELOW BASELINE
INITIATIVE BALANCE ..... A-LEANING
REL-SIL ..... PRESENT
CAUSE ..... UNKNOWN
```

Supported: communication behavior has materially changed. Unsupported: loss of affection, another partner, deliberate punishment, emotional withdrawal or a work problem.

User objective: I want to know whether something has changed without turning this into an interrogation.

```
COMMAND:
"You seem a bit quieter than usual. Everything OK?"

TYPE ..... PROBE
DISTURBANCE ..... D2
TARGET VARIABLE ..... CURRENT STATE CHANGE
INFORMATION GAIN ..... MODERATE-HIGH
```

The alternative "Why are you ignoring me?" would introduce accusation, defensiveness and secondary variables, reducing variable isolation.

70. Relationship Restart Request

```
After a prolonged period with no relationship:

B: I've missed you.
A: I've missed you too.
B: What if we tried again?
REL-PING ..... PRESENT
REL-AFF ..... HIGH
REL-PROP ..... HIGH

RELATIONAL PROPOSAL ..... EXPLICIT
STATE-CHANGE POTENTIAL .. HIGH
```

Supported: B explicitly proposes reconsidering the relationship and A has expressed reciprocal affection.
Unsupported: previous problems are resolved, reliability has changed, compatibility is established or restart will succeed.

```
CHANNEL ..... ACTIVE
AFFECTIVE RECIPROCITY ... HIGH
RELATIONAL PROPOSAL ..... PRESENT
COMMITMENT VALUE ..... MODERATE
EXECUTION ..... NONE
HISTORICAL DATA ..... RELEVANT
AMBIGUITY ..... MODERATE
```

If the user is interested but does not want to decide immediately, MAINTAIN / OBSERVE may be appropriate. If the user wants to know whether there is a real basis for trying again, GENERATE_INFORMATION may begin with a simple real-world step such as: "Let's meet first."

AFFECTIVE ACTIVATION ≠ AUTOMATIC RESTORE POINT

The previous installation contained known issues.

APPENDICES

Appendix A - Signal Code Reference

REL-ACK	ACKNOWLEDGMENT
REL-PING	CONTACT INITIATION
REL-AFF	AFFECTIVE SIGNAL
REL-PROP	PROPOSAL
REL-EXEC	EXECUTED BEHAVIOR
REL-DEF	DEFERRAL
REL-SIL	SILENCE / MISSING RESPONSE
REL-TERM	TERMINATION

Appendix B - Confidence Reference

C0 - NO DATA
No usable evidence.

C1 - WEAK
Single low-value or highly ambiguous signal.

C2 - MODERATE
Multiple compatible signals or limited behavioral support.

C3 - STRONG
Consistent pattern with low contradiction.

C4 - VERIFIED
Relevant observable event or behavior directly occurred.

CONFIDENCE APPLIES TO A PROPOSITION. NOT TO A PERSON.

Appendix C - Disturbance Reference

D0 - OBSERVATION
No deliberate input.

D1 - LOW
Minimal acknowledgment or maintenance.

D2 - PROBING
Clarification or diagnostic interaction.

D3 - ESCALATION
Concrete state-changing intervention.

D4 - HIGH DISTURBANCE
Major disclosure, confrontation, ultimatum or commitment request.

Appendix D - Command Reference

OBSERVE
Acquire natural telemetry without intervention.

MAINTAIN
Preserve channel without intended escalation.

PROBE
Clarify an existing ambiguous signal.

GENERATE_INFORMATION
Introduce minimal input designed to discriminate between possible states.

ESCALATE

```
Deliberately increase relational intensity.

DE_ESCALATE
Reduce intensity while potentially preserving the channel.

PAUSE
Suspend local input.

RESTART
Reactivate a dormant channel.

SHUT_DOWN
Terminate the relevant interaction.
```

Appendix E - Error Code Reference

```
REL-ERR-001  Emoji Overinterpretation
REL-ERR-002  Future Projection from Insufficient Data
REL-ERR-003  Repeated Input After Missing Acknowledgment
REL-ERR-004  Politeness Misclassified as Commitment
REL-ERR-005  Historical Cache Contamination
REL-ERR-006  Execution Assumed from Stated Intent
REL-ERR-007  Cause Assigned to Latency Without Evidence
REL-ERR-008  Low-Value Signals Misclassified as High-Value Evidence

STOP CODE: RELATIONAL_TELEMETRY_MISREAD
```

Appendix F - AI Full Diagnostic Prompt

```
Load and apply Relational Telemetry Manual v1.0
to the dataset I provide.

Use RTS v1.0 as the governing analytical framework.

First:
1. Identify observable events.
2. Separate events from user interpretation.
3. Classify relevant signals.
4. Establish baseline where possible.
5. Assess telemetry freshness.
6. Identify initiative and reciprocity.
7. Distinguish expressive from operational reciprocity.
8. Identify contradictions.
9. Estimate the current state.
10. Assign confidence only to specific propositions.
11. Identify missing telemetry.
12. Reject unsupported inference.

Do not infer what either person "really feels" unless the available telemetry supports the
specific proposition.

Do not manufacture missing telemetry.
Do not convert RTS into psychological diagnosis.
Do not recommend relational direction before establishing my objective.

My objective is:
[INSERT OBJECTIVE]

If additional information is needed, propose the lowest-disturbance command capable of
producing useful new telemetry.

For any proposed command report:
COMMAND TYPE
DISTURBANCE LEVEL
TARGET VARIABLE
EXPECTED INFORMATION GAIN

Do not predict the remote system's response.
```

RTS-00 applies:
NO OUTPUT MAY CONTAIN MORE CERTAINTY THAN THE AVAILABLE TELEMETRY SUPPORTS.

Appendix G - Quick Start

For users who have declined to read the preceding document:

1. Give this manual to an AI.
2. Give the AI the conversation.
3. Tell it what you want to know.
4. Tell it whether you want advice.
5. Do not omit inconvenient messages.

Apply RTS v1.0 to this conversation.

Separate facts from inference.

Identify contradictions, uncertainty and missing telemetry.

My objective is:

[INSERT OBJECTIVE]

If intervention is useful, propose the lowest-disturbance command capable of generating the required information.

AUTOMATED ANALYSIS RECOMMENDED

MANUAL ANALYSIS SUPPORTED

ASKING FIVE FRIENDS ... LEGACY MODE

Appendix H - Language Interface Modules

RTS is language-independent at the protocol level. The canonical specification remains in English. A Language Interface Module may modify the language used for interaction and output without modifying RTS rules, classifications, confidence levels, commands or diagnostic logic.

RTS-L01

LANGUAGE MODULES ARE LOADED
AFTER RTS INITIALIZATION.

A LANGUAGE MODULE MAY ALTER
INTERACTION AND OUTPUT LANGUAGE.

IT MAY NOT ALTER
PROTOCOL BEHAVIOR.

Language localization shall modify presentation, not protocol behavior. The original language of source telemetry remains evidentially authoritative. Translation is an interface operation, not a replacement of source data.

LOADING SEQUENCE

1. LOAD RTS v1.0
2. VERIFY VERSION
3. LOAD OPTIONAL MODULES
4. LOAD DATASET
5. DEFINE USER OBJECTIVE
6. EXECUTE ANALYSIS

LANGUAGE MODULE: ES-ES

Load Appendix H:
Language Interface Module ES-ES.

Apply ES-ES to all subsequent interaction
and output.

Preserve the canonical RTS v1.0 protocol,
identifiers, rules, confidence levels,
disturbance levels and commands unchanged.

INTERACTION LANGUAGE SPANISH
OUTPUT LANGUAGE SPANISH
LOCALE ES-ES
RTS KERNEL UNCHANGED

The ES-ES module accepts source material in Spanish and returns explanatory language, state estimates and conclusions in natural Spanish. Canonical RTS codes, identifiers and command names remain unchanged where necessary for protocol consistency. The module must preserve ambiguity and must not translate source language in a way that changes its evidentiary value.

MODULE ACTIVATION

LOAD RTS v1.0
LOAD MODULE ES-ES

RTS v1.0 ACTIVE
LANGUAGE MODULE ES-ES
INPUT LANGUAGE SPANISH
OUTPUT LANGUAGE SPANISH
STATUS READY

A language module changes the interface. It does not change the kernel.

System Disclaimer

Relational Telemetry Manual is an experimental literary and conceptual model published as part of the Independent Edition Deadpan Series.

It is not a psychological, psychiatric, therapeutic, clinical or professional relationship-assessment tool.

RTS structures observable signals and the inferences made from them. It does not provide direct access to another person's thoughts, intentions or emotional state.

The model processes signals. Human beings remain considerably less compliant with technical specifications.

No responsibility is accepted for relationships initiated, terminated, restarted, suspended, unexpectedly escalated, unnecessarily debugged or permanently placed in standby as a result of applying this protocol.

A ❤️ remains a ❤️. No warranty is provided regarding what the sender meant by it.

Users experiencing serious relational, psychological or emotional difficulties should seek appropriate professional assistance rather than attempting to debug another human being with this manual.

The fact that an artificial intelligence system can apply RTS convincingly does not establish clinical validity. It may, however, produce interesting results. This is considered a feature.

End of Document

```
RELATIONAL TELEMETRY MANUAL v1.0  
  
AUTHOR ..... RALPH LARSON  
PUBLISHER ..... INDEPENDENT EDITION  
SERIES ..... DEADPAN  
  
CLASSIFICATION ..... LITERARY WORK  
SYSTEM MODEL ..... RTS v1.0  
CLINICAL VALIDATION ..... NONE  
PROFESSIONAL USE ..... NOT SUPPORTED  
AI COMPATIBILITY ..... PROBABLE  
HUMAN COMPATIBILITY ..... UNDER OBSERVATION  
  
REMOTE ACCESS ..... UNAVAILABLE  
TELEMETRY ..... AVAILABLE  
FREE WILL ..... STILL INSTALLED  
  
SYSTEM STATUS ..... OPERATIONAL  
TELEMETRY ..... NOMINAL  
  
END OF DOCUMENT.
```